

M.Sc. course „Computational Engineering”

Summer 2001

Advanced Finite Element Methods

Written Examination on 6.8.2001

Last name: _____ First name: _____
 (please write legibly)

exercise no.	1	2	3	4	sum
max. points	40	47	47	46	180
obtained points					

Important instructions

- Duration: 3 hours,
first 40 minutes without,
2 hours and 20 minutes with appliance.
- Proof the completeness of the exercises.
- Write your name onto all pages of the test.
- Write the solutions of part 1 of the exam directly onto the handout.
Don't use your own paper.
- Hand in all pages of the examination.
- The solutions should include all auxiliary calculations.
- Programmable pocket calculators are only allowed without programs.
- The use of laptops or notebooks is not allowed.

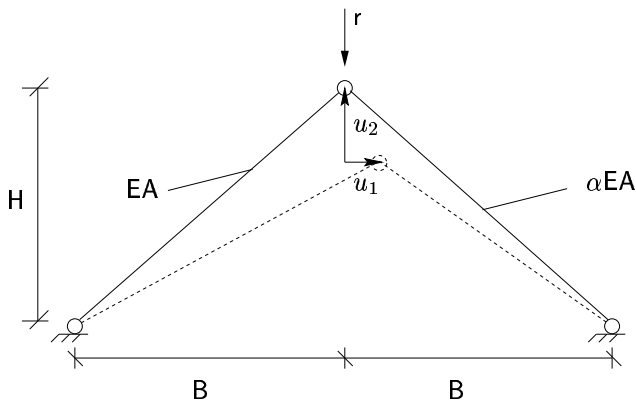
Exercise: 2max. Σ points: 47obtained. Σ points:

The equilibrium condition of the shown system can be formulated by the following equations:

$$\begin{aligned} \mathbf{r}_i(\mathbf{u}) &= \mathbf{r} \\ \mathbf{r}_i(\mathbf{u}) &= \frac{EA}{2L^3} \left\{ (\mathbf{X} + \mathbf{u}) [(2\mathbf{X} + \mathbf{u}) \cdot \mathbf{u}] + \alpha (\bar{\mathbf{X}} + \mathbf{u}) [(2\bar{\mathbf{X}} + \mathbf{u}) \cdot \mathbf{u}] \right\}, \end{aligned} \quad (1)$$

with

$$\mathbf{X} = \begin{bmatrix} B \\ H \end{bmatrix}, \quad \bar{\mathbf{X}} = \begin{bmatrix} -B \\ H \end{bmatrix}, \quad \mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}, \quad \mathbf{r} = \begin{bmatrix} 0 \\ -r \end{bmatrix}. \quad (2)$$



$$\begin{aligned} H &= 0.65 \text{ [m]} \\ B &= 1.0 \text{ [m]} \\ EA &= 2.1 \cdot 10^{-2} \text{ [KN]} \end{aligned}$$

Figure 1: Geometry and FE-model of the structure

a) Proof the following identity by means of the GATAUX derivative:

$$\frac{\partial}{\partial \mathbf{u}} \{ (\mathbf{X} + \mathbf{u}) [(2\mathbf{X} + \mathbf{u}) \cdot \mathbf{u}] \} = [(2\mathbf{X} + \mathbf{u}) \cdot \mathbf{u}] \mathbf{1} + 2(\mathbf{X} + \mathbf{u}) \otimes (\mathbf{X} + \mathbf{u}) \quad (3)$$

with

$$\mathbf{1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}. \quad (4)$$

- Compute the stiffness matrix $\mathbf{K}_T(\mathbf{u})$ for the nonsymmetric structure ($\alpha = 1.5$).
- Derive the equation of the NEWTON-RAPHSON iteration scheme by linearizing the weak form of equilibrium.
- Compute the deformation of the nonsymmetric system with a point load of $r = 1.2996 \cdot 10^{-3}$ using 2 iterations.
- Chose a convergence criterion and check the convergence.

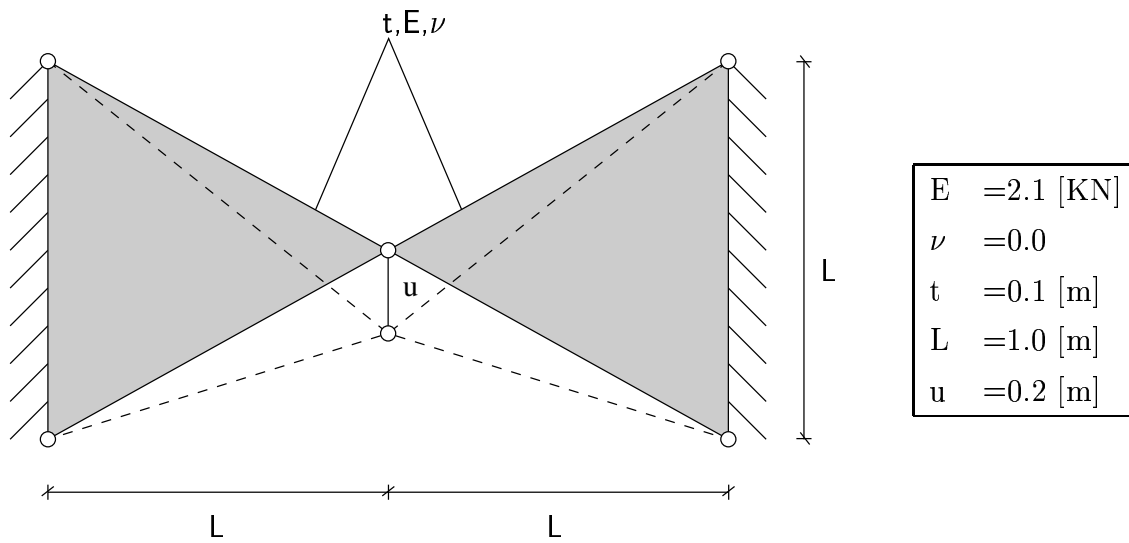
Exercise: 3max. Σ points: 47obtained. Σ points:

Figure 2: Geometry and FE-model of the structure

Compute the response of the 2-D structure illustrated in the figure. The material behavior can be described by a scalar damage model. The elastic domain is approximated by the standard HOOKE's law. A hyperbolic equation for the relation between the damage and the internal variable

$$d(\kappa) = 1 - \frac{0.1}{\kappa} \quad (5)$$

is investigated for the modeling of the post peak response. With the definition of an equivalent strain measure

$$\eta(\boldsymbol{\varepsilon}) = \sqrt{\boldsymbol{\varepsilon}^T \boldsymbol{\varepsilon}}, \quad (6)$$

the model is completed.

- Compute the approximated strains $\boldsymbol{\varepsilon}^T = [\varepsilon_{11}, \varepsilon_{22}, 2\varepsilon_{12}]$ using a 3 node plane stress triangular element (CST).
- Compute the current damage variable d .
- Compute the components $\boldsymbol{\sigma}^T = [\sigma_{11}, \sigma_{22}, \sigma_{12}]$ of the stress tensor.
- Proof the following lemma for CST elements and a scalar damage model ($\boldsymbol{\sigma} = (1-d) \mathbf{C} \boldsymbol{\varepsilon}$):

$$\mathbf{K}_d^T = (1-d) \mathbf{K}_{el}^T. \quad (7)$$

In Equation (7) \mathbf{K}_{el}^T is the element stiffness matrix of the undamaged structure, whereas \mathbf{K}_d^T takes stiffness degradation within the element into account.

Exercise: 4max. Σ points: 46obtained. Σ points:

The geometrically nonlinear analysis of a slab has resulted in the deformed shape in Fig. 3. The computation has been carried out by means of a four node finite element with bilinear displacement interpolations.

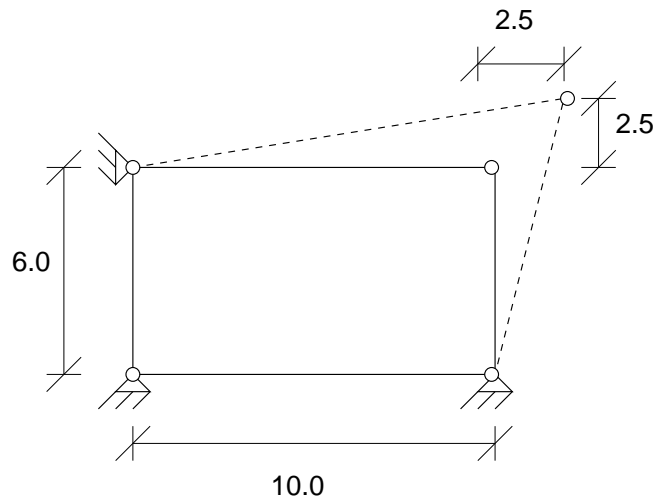


Figure 3: Reference and deformed configuration

The following aspects have to be addressed:

- Compute the JACOBI matrix and determinant.
- Compute the displacement field with respect to physical coordinates.
- Compute the deformation gradient.
- Compute the distribution of the density of the deformed configuration with respect to the density ρ_0 of the reference configuration.
- Compute the components E_{11} , E_{22} , E_{12} and E_{21} of the GREEN-LAGRANGE strain tensor.